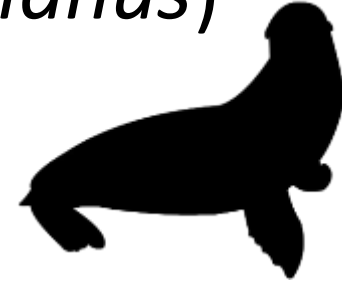


# The Biomechanical Energetics of Terrestrial Locomotion in California Sea lions (*Zalophus californianus*)



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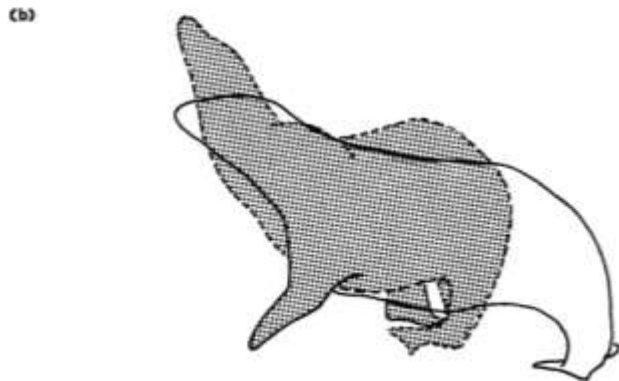
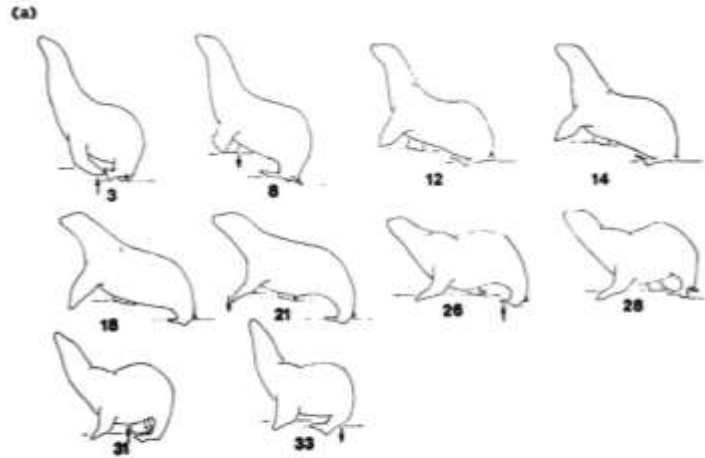
# *Zalophus californianus*

- California sea lions spend a large portion of their year on land to reproduce.
  - Pups stay with their mother for up to a year
- Highly maneuverable in the water, propelling themselves primarily with forelimbs
- Locomote efficiently on land



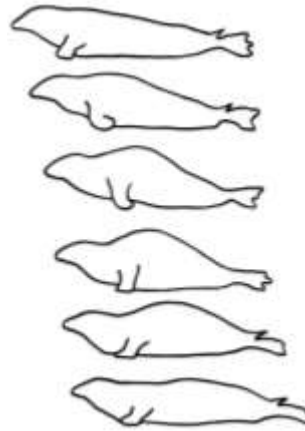
# Terrestrial Locomotion: The ability to “walk”

- California sea lions can pull their hindlimbs underneath them to walk and gallop.
- Elongated forelimbs aid in terrestrial and aquatic locomotion
- Limbs entirely support the weight of the body
- Flex their axial skeleton during forward locomotion



# Terrestrial Locomotion: The ability to “walk”

- Phocids cannot pull their hindlimbs beneath their body, and they do not have the elongated forelimbs to aid in terrestrial locomotion.
- Limbs do not support their weight and they rely on a forward lunge.
- During forward movement, phocids' trunks flex caudally to the chest, bringing the pelvis forward, thus pushing the anterior of the body forwards



# The Sea lions



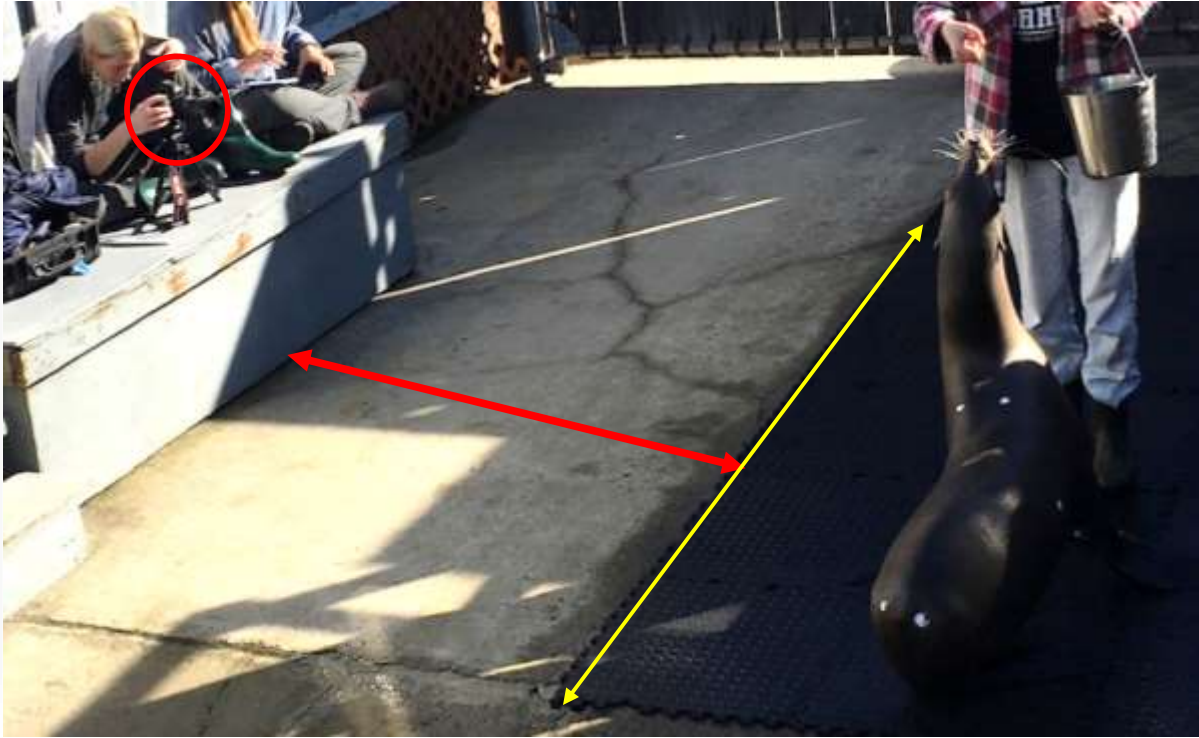
Ariel



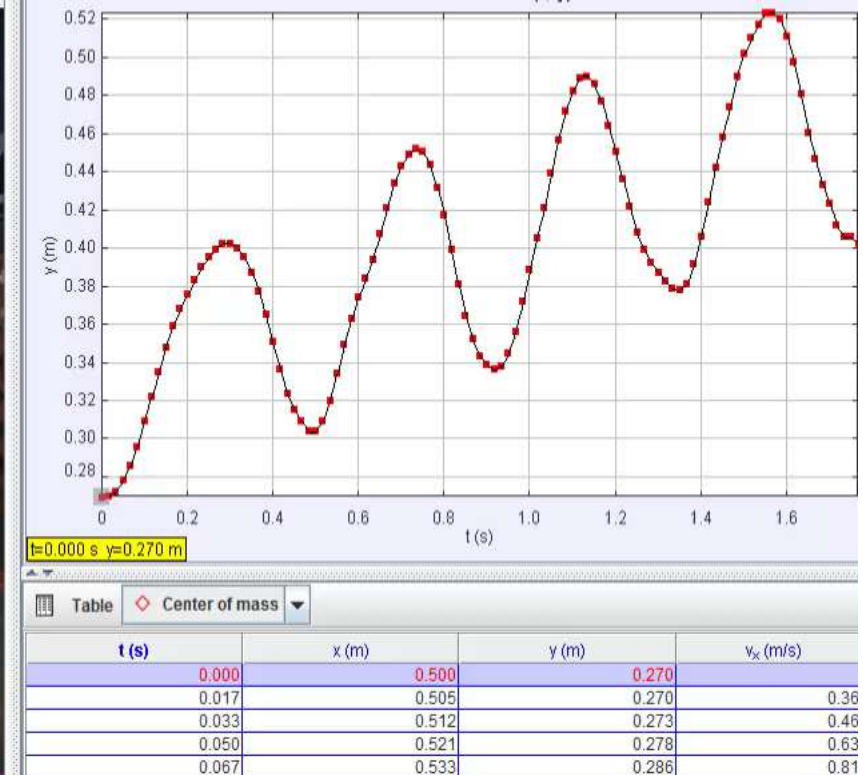
Nemo



Cali

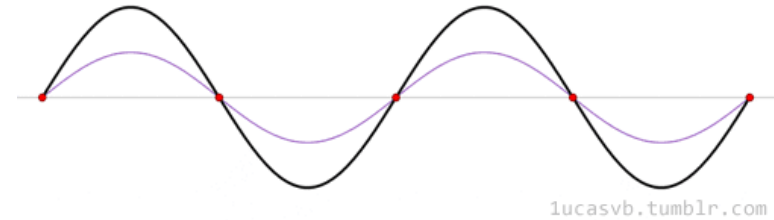


# Energetics



**Hypothesis:** The quadrupedal gait of the California sea lion will be more efficient, showing a lower mechanical Cost of transport, when compared to the undulatory gait of the three phocid seals.

# Energetics Equations



Variables input into the model included  $x$  (horizontal displacement) and  $y$  (vertical displacement) of marked body points,  $BL$  (body length),  $M$  (mass), absolute and transverse  $V$  (velocity),  $f$  (stride frequency), and  $A$  (vertical amplitude of their oscillations).

The average power, ( $P$ ), which is the average rate at which both kinetic and potential energies are used by the animal, is then:

$$P = 2 \left( \frac{dK}{dt} \right) = \frac{1}{2} \mu V \omega^2 A^2 = 2\pi^2 \mu V f^2 A^2$$

This model assumes that the animal is moving over flat ground. Cost of transport (COT) was determined by dividing the mass ( $M$ ) and velocity ( $V$ ) of the animals by their power output ( $P$ ) in the following equation:

$$COT = P/M/V$$

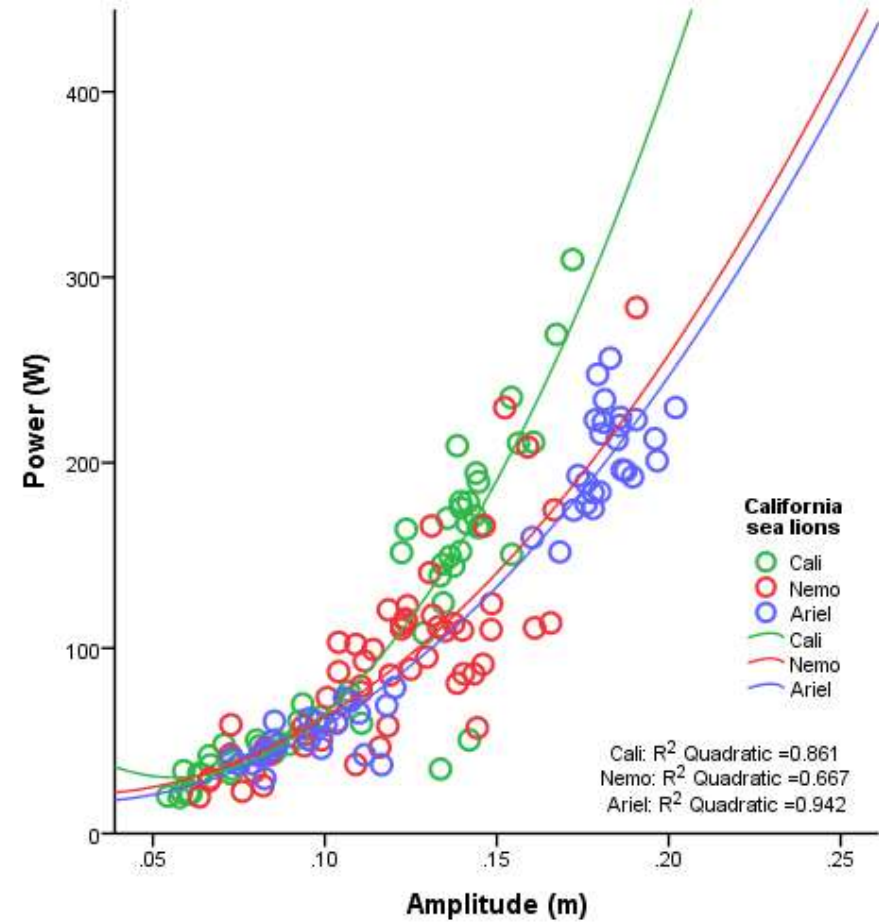
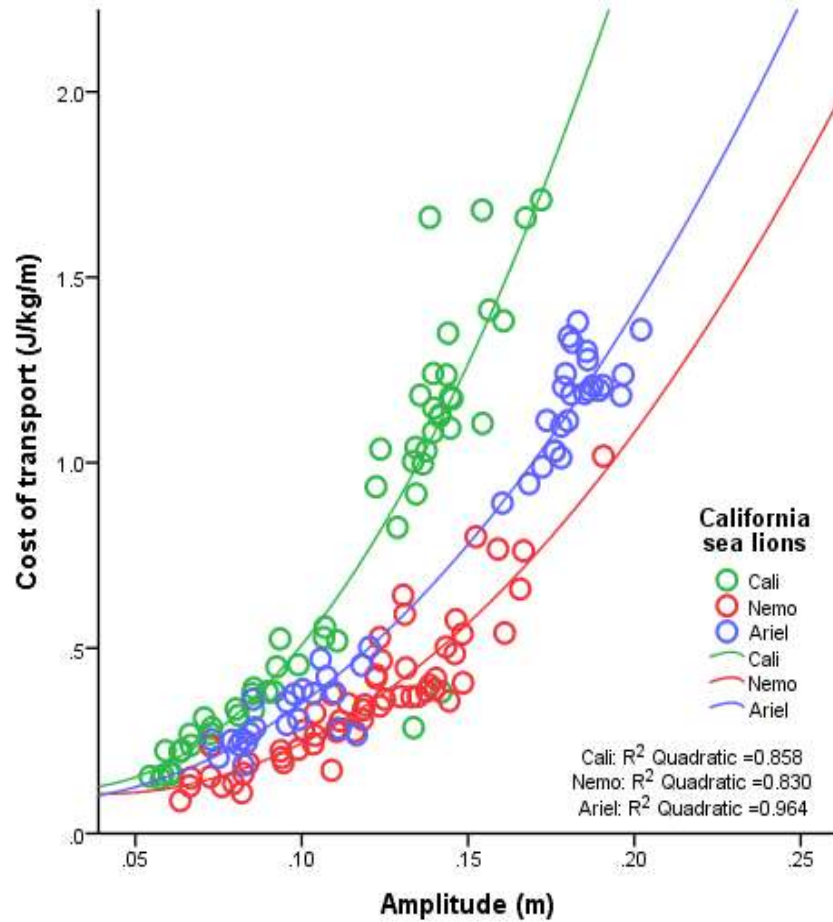
Average Power output between the three sea lions was 112 watts

	<b>Power</b>	<b>Cost of transport</b>	<b>Amplitude</b>	<b>Velocity</b>
	<i>W</i>	<i>J/kg/m</i>	<i>m</i>	<i>m/s</i>
<b>Cali</b>	111.42±73.48	0.76±0.48	0.11±0.04	1.95±0.18
<b>Nemo</b>	93.41±51.73	0.37±0.19	0.12±0.029	1.78±0.32
<b>Ariel</b>	131.28±79.26	0.76±0.44	0.14±0.05	2.01±0.15
<b>Mean</b>	112.04±18.94	0.63±0.23	0.12±0.02	1.92±0.12

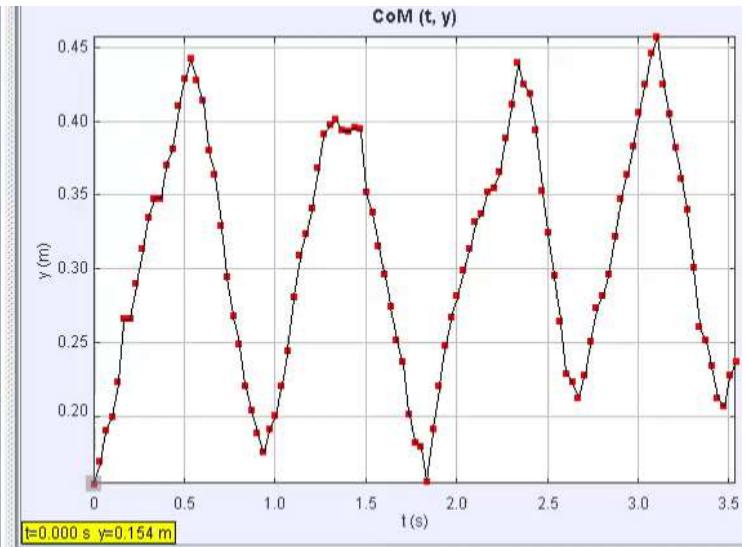
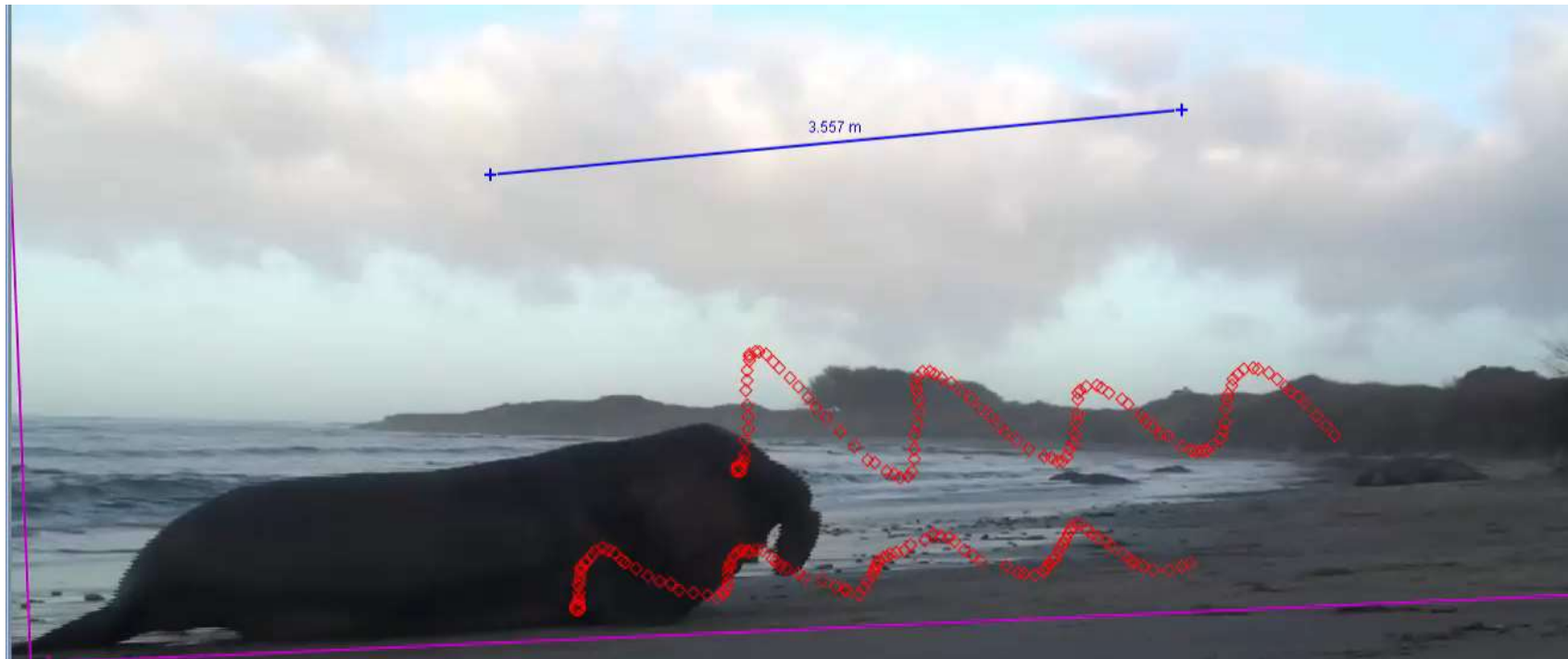




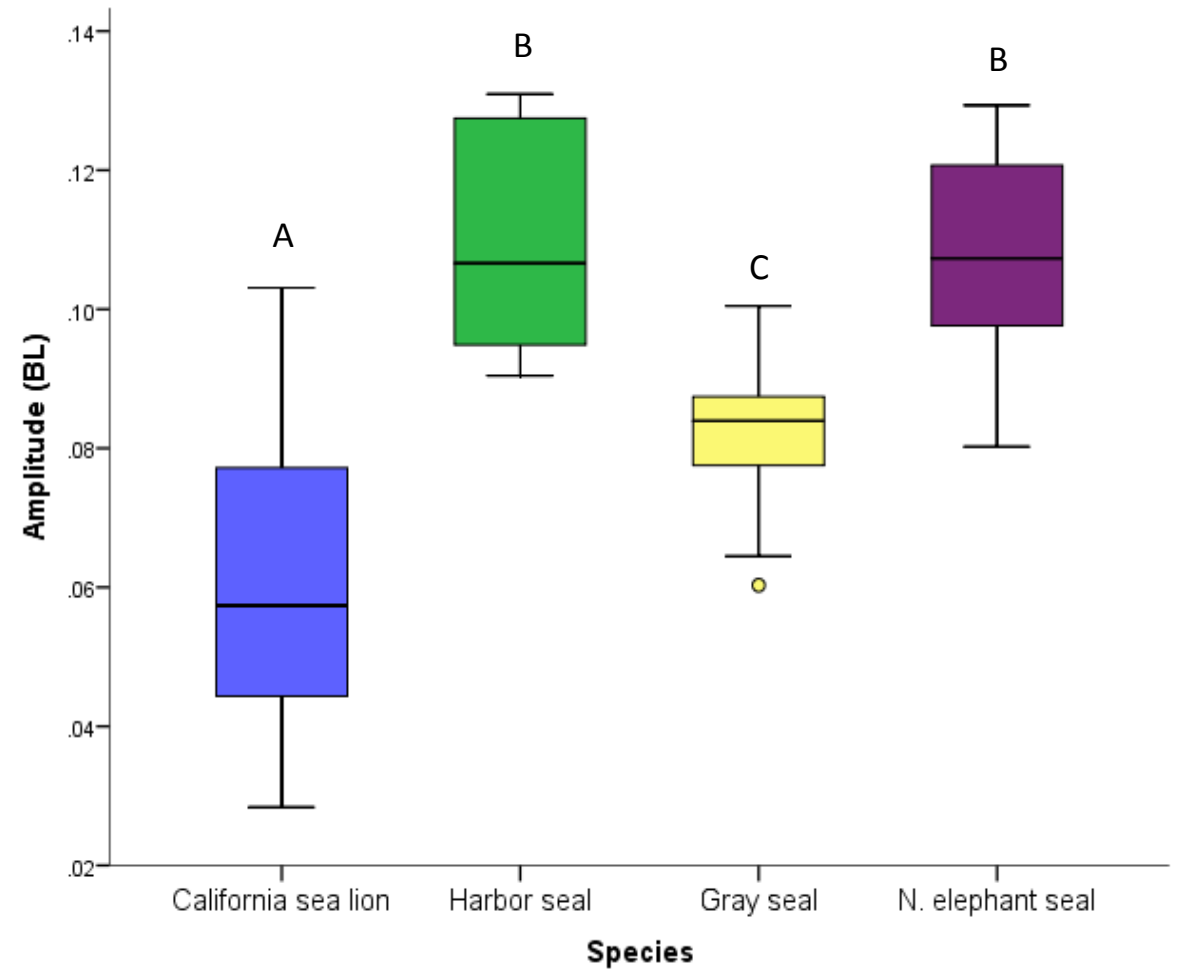
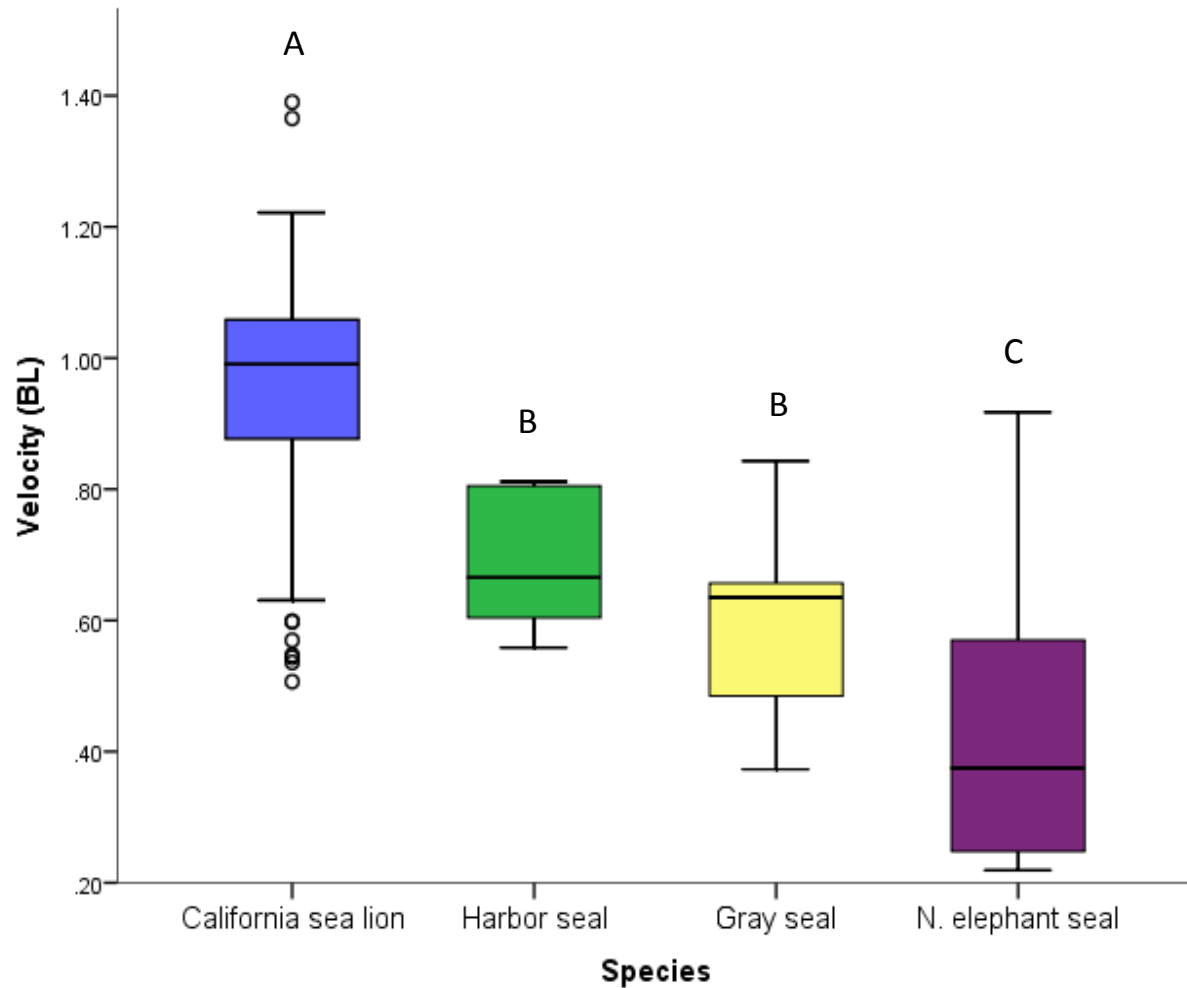
# Positive correlation between COT and power output



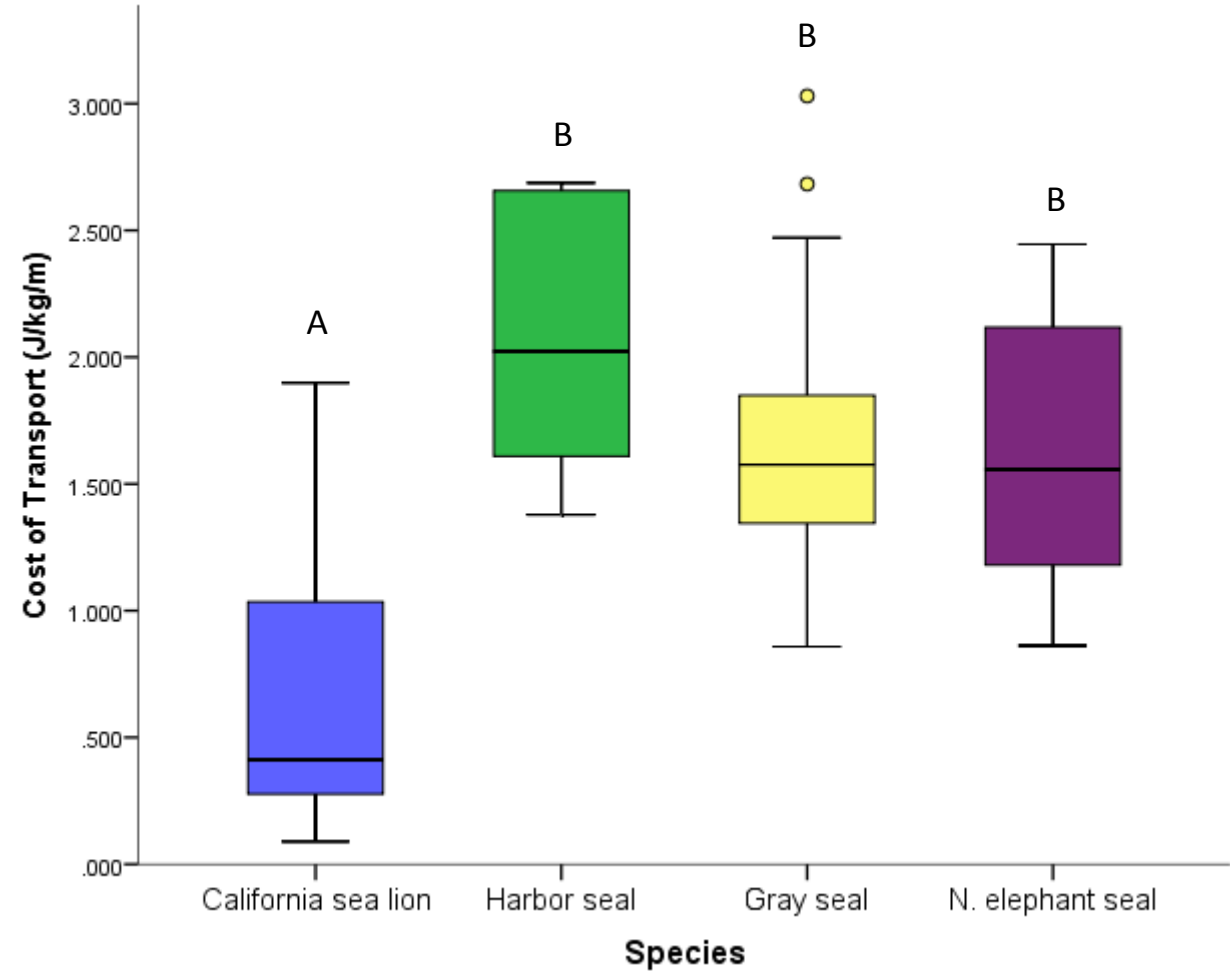
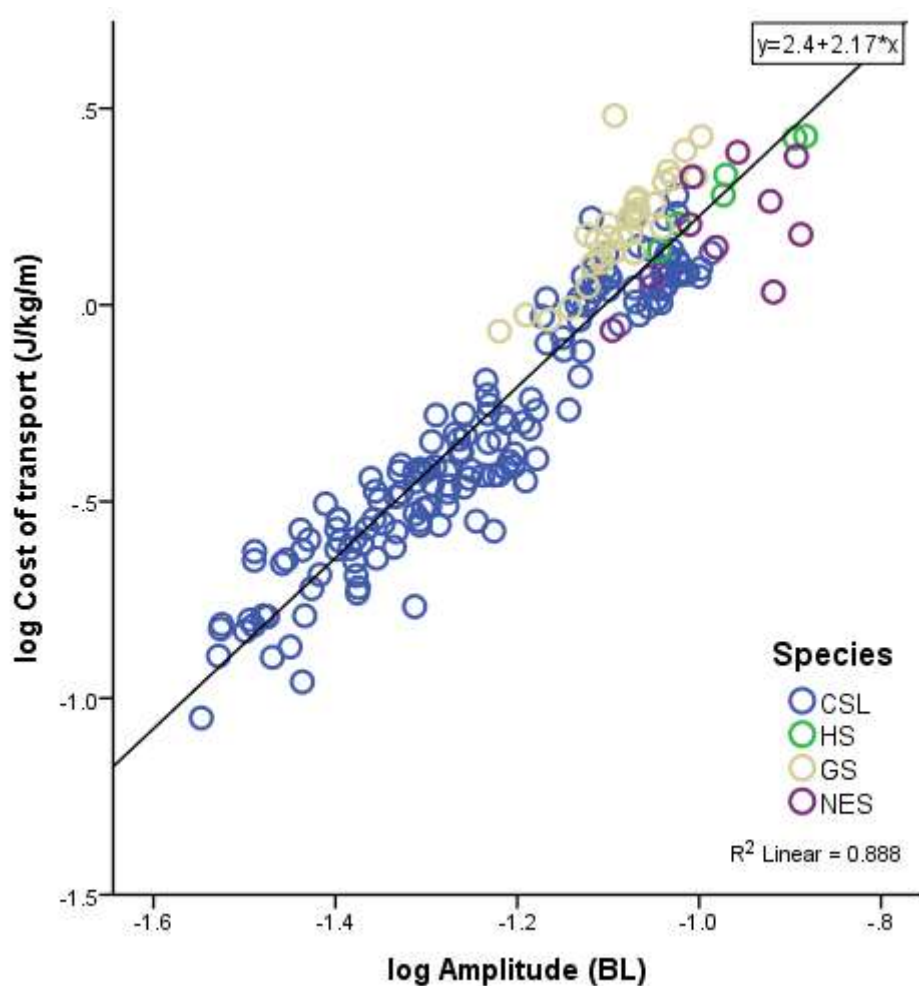
The Northern elephant seals had a Cost of Transport of 1.64 J/kg/m with a Power output of 2,762.41 W



California sea lions had a significantly faster velocity and a lower vertical displacement



California sea lions had a significantly lower Power outputs and a lower Cost of transport



# Galloping Efficiency

2.06 J/kg/m



0.63 J/kg/m



0.35 J/kg/m



## Conclusions

- California sea lions have the ability to pull their hindlimbs underneath their body to gallop on land
- Sea lions move over land with higher velocities, smaller vertical amplitudes, and thus significantly lower costs of transport and power outputs.
- California sea lion do locomote more efficiently, their gait more similar to the efficient gait of a terrestrial mammal.



# Questions?

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